

Buses are divided into three types-

- (i) Load bus
- (ii) Generator bus
- (iii) Slack bus

- For load bus, real power ( $P$ ) & reactive power  $Q$  are known but magnitude & phase angle of bus voltage is unknown.

- Generator bus (voltage controlled bus) is connected with generator. Therefore bus voltage corresponds to generation voltage & active power generation corresponding to generator rating is specified for this bus.

- Slack bus (swing or reference bus) doesn't exist in real life. To supply power loss, an extra generator bus is considered for which bus magnitude & voltage is specified.

Algorithm of NR method-

- (i) for  $Y$ -bus matrix
- (ii) Assume initial bus voltage mag.  $|V_i|$

& phase angle  $\sigma_i$ .  $|V_1| = 1 \text{ pu}$  &  $\sigma_1 = 0 \text{ rad}$ .

(iii) Set iteration count 0.

(iv) Calculate real & reactive power for each load buses.

(v) Compute errors for each load bus.

(vi) Calculate Jacobian matrix

(vii) Obtain value of  $\Delta|V_i|$  &  $\Delta\sigma_i$

(viii) Find value of  $|V_i|$  &  $\sigma_i$  & next iteration starts

(ix) Continue until ~~the~~ scheduled error for all load buses.

(x) Calculate line flows & power at slack bus.