1.11	Operating system can be said as a collect	ion of a selection and lead to all selection of a s	
	(a) hardware components	(b) software routines	
		(d) All of these.	
1 12	The operarting system manages		-
	(a) memory	(b) processor	
	(c) disk and I/O devices	(d) All of these.	
1 12	A computer cannot "boot" if it does not ha		
1.13	(a) compiler	(b) loader	
	(c) operating system	(d) assembler.	
1 14	Software that measures, monitors, analys		
1.14	(a) system software	(b) according activiare	
	(c) real time software	(d) business software.	
	。	THE MEN WAS DESCRIBED THE PROPERTY OF THE WAY	
1.15	Which of the following is characteristics o	(b) Memory management	
	(a) Resource management	(d) All of these.	
	(c) Error recovery	marks taken til	
1.16	Multiprocessing models have	(a) Real time system	
	(a) symmetric multiprocessing model	(b) unsymmetric multiprocessing model	
•	(c) Both (a) and (b) above	(d) None of the above.	
1.17			
		(b) manage resources	
	(c) provide utilities	(d) be user friendly.	
1.18	Remote computing services involves the u	use of time-sharing and	
		(b) interactive processing	
		(d) real time processing.	
1.19	Real time system are		
	(a) primarily used on mainframe comput	ters assumed expression after an are self-with the	
	(b) used for monitoring events as they oc	personal computers (PG), recessors rupo	
THEFT	(c) used for program analysis		
	(d) used for real time interactive users.		
1.20		rogram at a time, the system software we are usi	ng
	must be capable of	shedid include applications such as web he	
		(b) virtual memory	4
		(d) multi-tasking.	
1.21	Which of the following is not an advantag	ge of multiprocessing ?	
	(a) Increased throughput	(b) shorter response time	
	(c) Decrease operating system overhead	(d) Ability to assign priorities of jobs.	
1.22	Main function of distributed system is		
	(a) Resource sharing	(b) Compilation speed up	
	(c) Reliability	(d) All of these.	
1.23	Which of the following is not a part of ope	erating system	
	(a) Supervisor	(b) Performance monitor	
	(c) Job control program	(d) I/O control program.	
1.24	An example of hard real time system.		
	(a) robotics	(b) individual control	
	(c) Both (a) and (b)	(d) None of the above.	